

# A generic algorithm for efficient key recovery in differential attacks – and its associated tool

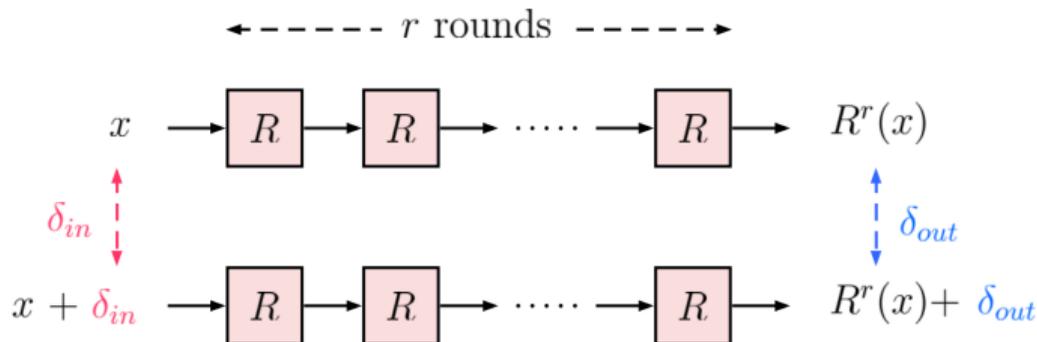
Christina Boura, Nicolas David, Patrick Derbez, Rachelle Heim Boissier, María Naya-Plasencia

UVSQ, Inria, University of Rennes

Eurocrypt 2024, Zurich, Switzerland

# Differential cryptanalysis

- Cryptanalysis technique introduced by [Biham](#) and [Shamir](#) in **1990**.
- Based on the existence of a high-probability **differential**  $(\delta_{in}, \delta_{out})$ .



- If the probability of  $(\delta_{in}, \delta_{out})$  is (much) higher than  $\max(2^{-n}, 2^{-\kappa})$ , where  $n$  is the block size,  $\kappa$  the key length, then we have a **differential distinguisher**.

# Key recovery attack

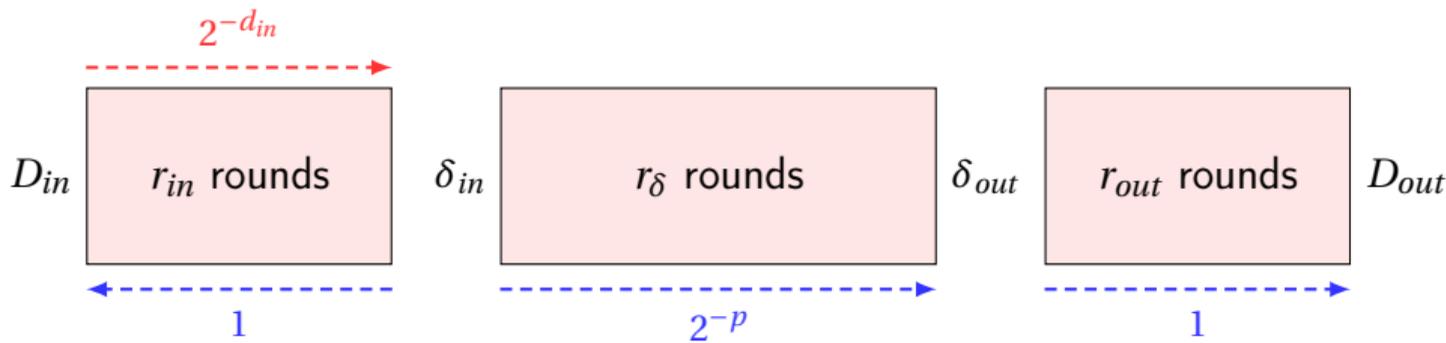
---

A differential distinguisher can be used to mount a **key recovery** attack.

- This technique broke many block ciphers of the 70s-80s, e.g. **DES, FEAL, etc.**
- New primitives should come with arguments of resistance **by design** against this technique.
- Most of the arguments used rely on showing that **differential distinguishers of high probability do not exist** after a certain number of rounds.
- Not always enough: A **deep understanding of how the key recovery works** is necessary to claim resistance against these attacks.

# The key recovery problem

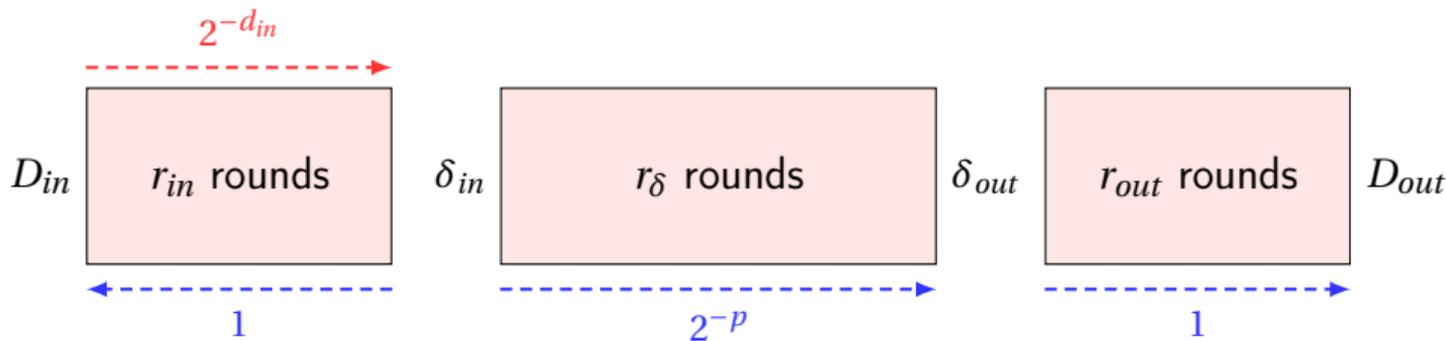
# Overview of the key recovery procedure



**First step:** Construct  $2^{p+d_{in}}$  pairs  $((P, C), (P', C'))$  s.t.  $P + P' \in D_{in}$ .

- Use of **structures** of size  $2^{d_{in}}$  → **Data complexity:**  $\approx 2^{p+1}$ , **Memory complexity:**  $2^{d_{in}}$

# Overview of the key recovery procedure



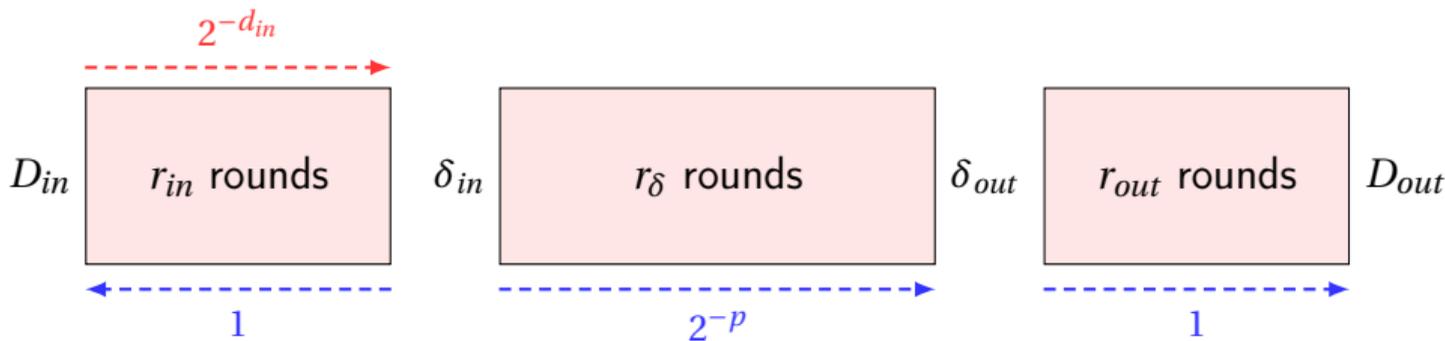
**First step:** Construct  $2^{p+d_{in}}$  pairs  $((P, C), (P', C'))$  s.t.  $P + P' \in D_{in}$ .

- Use of **structures** of size  $2^{d_{in}}$  → **Data complexity:**  $\approx 2^{p+1}$ , **Memory complexity:**  $2^{d_{in}}$

**Second step:** Discard pairs that are **not in**  $D_{out}$ .

- **Number of pairs** for the attack:  $N = 2^{p+d_{in}-(n-d_{out})}$

# Overview of the key recovery procedure



**First step:** Construct  $2^{p+d_{in}}$  pairs  $((P, C), (P', C'))$  s.t.  $P + P' \in D_{in}$ .

- Use of **structures** of size  $2^{d_{in}}$  → **Data complexity:**  $\approx 2^{p+1}$ , **Memory complexity:**  $2^{d_{in}}$

**Second step:** Discard pairs that are **not in**  $D_{out}$ .

- **Number of pairs** for the attack:  $N = 2^{p+d_{in}-(n-d_{out})}$

**Third step:** Core key recovery

# Core key recovery

## Goal

Determine the pairs for which there exists an **associated key** that leads to the differential.

A **candidate** is a triplet  $((P, C), (P', C'), k)$  such that the (partial) key candidate  $k$  encrypts (resp. decrypts)  $(P, P')$  (resp.  $(C, C')$ ) to the input (resp. output) of the differential.

# Core key recovery

## Goal

Determine the pairs for which there exists an **associated key** that leads to the differential.

A **candidate** is a triplet  $((P, C), (P', C'), k)$  such that the (partial) key candidate  $k$  encrypts (resp. decrypts)  $(P, P')$  (resp.  $(C, C')$ ) to the input (resp. output) of the differential.

What is the **complexity** of this procedure?

- **Upper bound:**  $\min(2^k, N \cdot 2^{|\mathcal{K}|})$ ,
- **Lower bound:**  $N + N \cdot 2^{|\mathcal{K}| - d_{in} - d_{out}}$ ,  
where  $N \cdot 2^{|\mathcal{K}| - d_{in} - d_{out}}$  is the **number of expected candidates**.

# Core key recovery

## Goal

Determine the pairs for which there exists an **associated key** that leads to the differential.

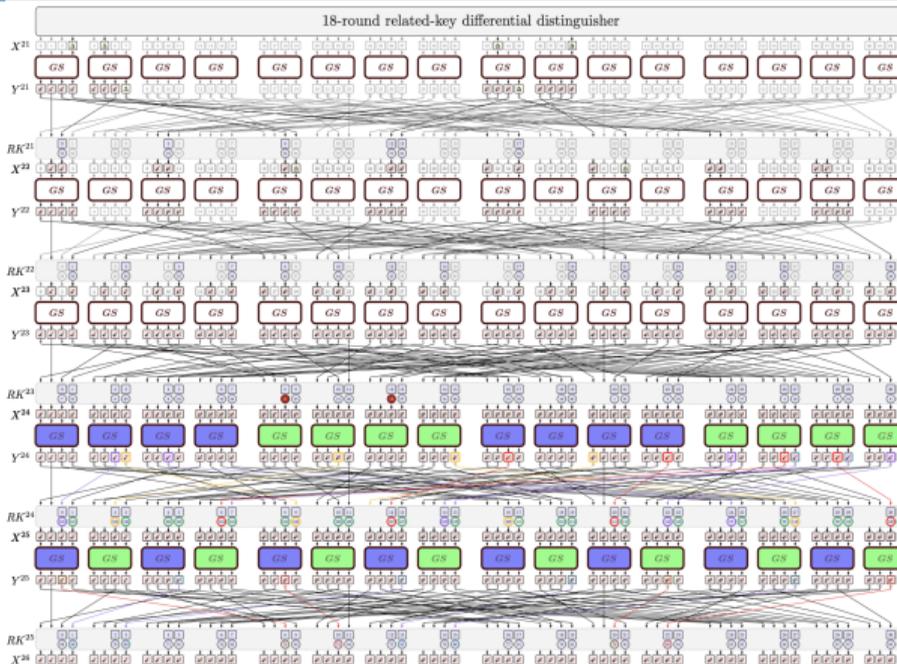
A **candidate** is a triplet  $((P, C), (P', C'), k)$  such that the (partial) key candidate  $k$  encrypts (resp. decrypts)  $(P, P')$  (resp.  $(C, C')$ ) to the input (resp. output) of the differential.

What is the **complexity** of this procedure?

- **Upper bound:**  $\min(2^k, N \cdot 2^{|\mathcal{K}|})$ ,
- **Lower bound:**  $N + N \cdot 2^{|\mathcal{K}| - d_{in} - d_{out}}$ ,  
where  $N \cdot 2^{|\mathcal{K}| - d_{in} - d_{out}}$  is the **number of expected candidates**.

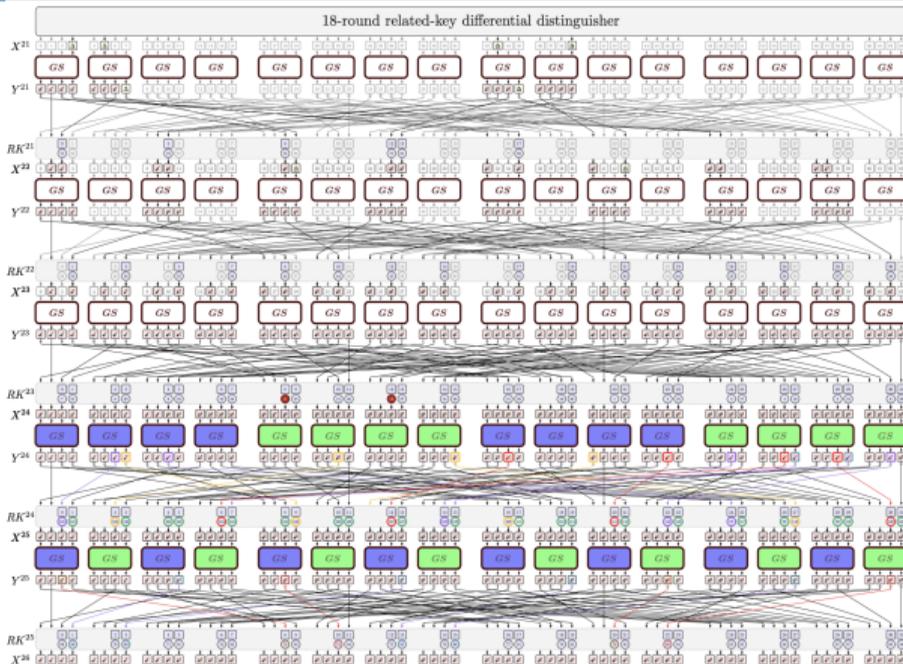
A key recovery is **efficient**, if its complexity is as close as possible to the **lower bound**.

# The key recovery problem



Potentially **too many active S-boxes** and **key guesses**.

# The key recovery problem



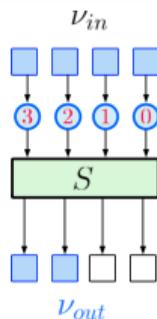
**Our goal** : Automate the key recovery for **SPN** block ciphers with a **bit-permutation** as linear layer and an **(almost) linear key schedule**.

# Efficient key recovery

## Solving an active S-box $S$

Determine the triplets  $(x, x', k)$  s. t.  $x + x' \in \nu_{in}$  and  $S(x + k) + S(x' + k) \in \nu_{out}$ .

Discard the other triplets.



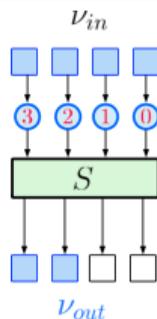
**Example:** this active S-box has  $2^{8+4-2} = 2^{10}$  solutions.

# Efficient key recovery

## Solving an active S-box $S$

Determine the triplets  $(x, x', k)$  s. t.  $x + x' \in \mathcal{V}_{in}$  and  $S(x + k) + S(x' + k) \in \mathcal{V}_{out}$ .

Discard the other triplets.



Can be generalised to any subset of active S-boxes!

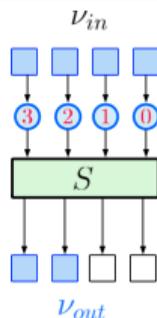
**Example:** this active S-box has  $2^{8+4-2} = 2^{10}$  solutions.

# Efficient key recovery

## Solving an active S-box $S$

Determine the triplets  $(x, x', k)$  s. t.  $x + x' \in \nu_{in}$  and  $S(x + k) + S(x' + k) \in \nu_{out}$ .

Discard the other triplets.



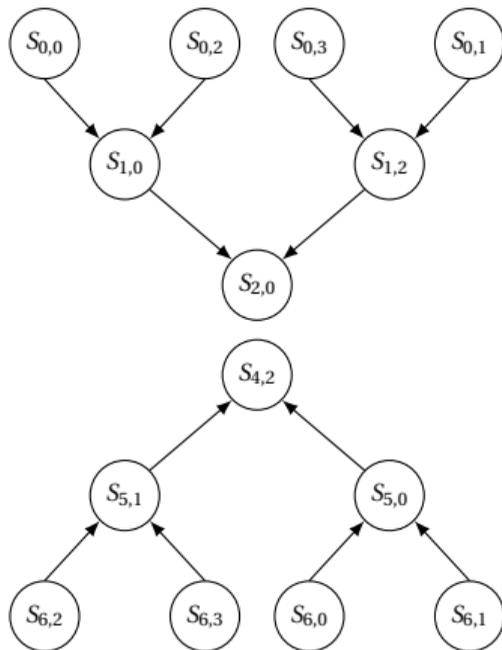
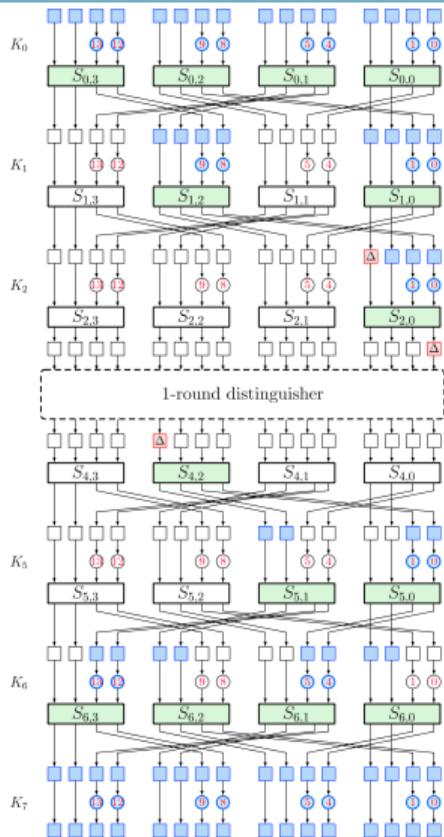
Can be generalised to any subset of active S-boxes!

**Example:** this active S-box has  $2^{8+4-2} = 2^{10}$  solutions.

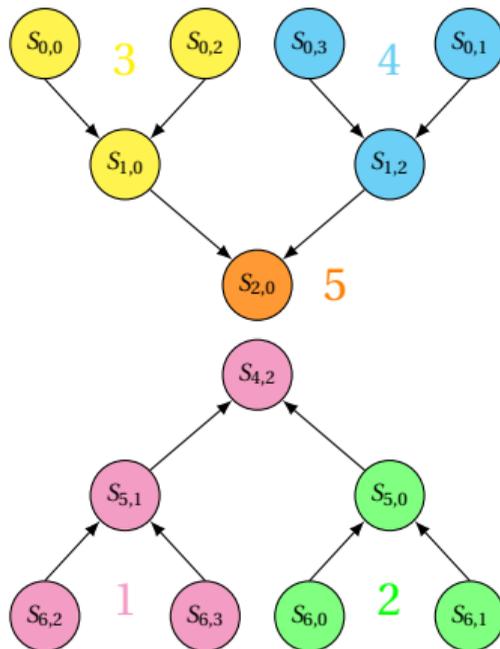
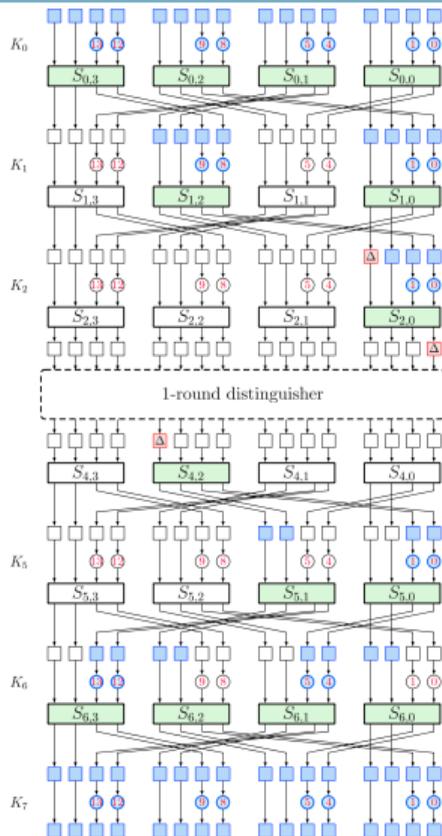
**Goal:** Reduce the number of triplets as early as possible whilst maximizing the number of determined key bits in the involved key material  $\mathcal{K}$ .

# An algorithm for efficient key recovery

# Modeling the key recovery as a graph



# Modeling the key recovery as a graph



**Key recovery:**  
partition of the nodes + associated order

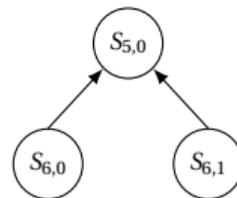
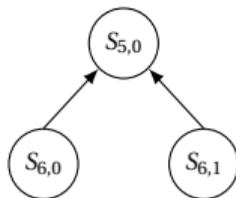
# Considering strategies

## Strategy $\mathcal{S}_X$ for a subgraph $X$

Procedure that allows to **enumerate** all the possible values that the S-boxes of  $X$  can take **under the differential constraints** imposed by the distinguisher.

**Parameters** of a strategy  $\mathcal{S}_X$ :

- number of solutions  $\mathcal{N}$ ;
- online time complexity  $\mathcal{T}$ .



A strategy can be further refined with extra information: e.g. **memory**, **offline time**.

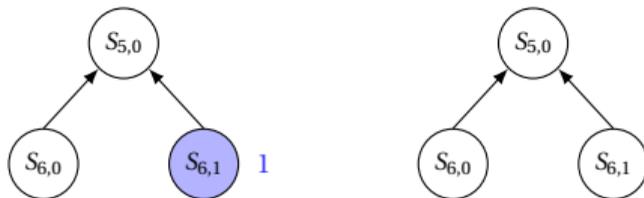
# Considering strategies

## Strategy $\mathcal{S}_X$ for a subgraph $X$

Procedure that allows to **enumerate** all the possible values that the S-boxes of  $X$  can take **under the differential constraints** imposed by the distinguisher.

**Parameters** of a strategy  $\mathcal{S}_X$ :

- number of solutions  $\mathcal{N}$ ;
- online time complexity  $\mathcal{T}$ .



A strategy can be further refined with extra information: e.g. **memory**, **offline time**.

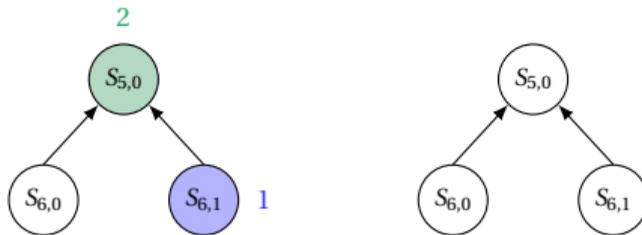
# Considering strategies

## Strategy $\mathcal{S}_X$ for a subgraph $X$

Procedure that allows to **enumerate** all the possible values that the S-boxes of  $X$  can take **under the differential constraints** imposed by the distinguisher.

**Parameters** of a strategy  $\mathcal{S}_X$ :

- number of solutions  $\mathcal{N}$ ;
- online time complexity  $\mathcal{T}$ .



A strategy can be further refined with extra information: e.g. **memory**, **offline time**.

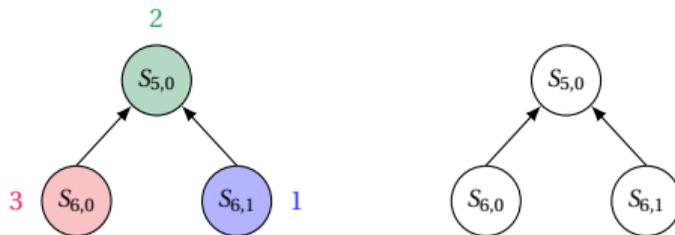
# Considering strategies

## Strategy $\mathcal{S}_X$ for a subgraph $X$

Procedure that allows to **enumerate** all the possible values that the S-boxes of  $X$  can take **under the differential constraints** imposed by the distinguisher.

**Parameters** of a strategy  $\mathcal{S}_X$ :

- number of solutions  $\mathcal{N}$ ;
- online time complexity  $\mathcal{T}$ .



A strategy can be further refined with extra information: e.g. **memory**, **offline time**.

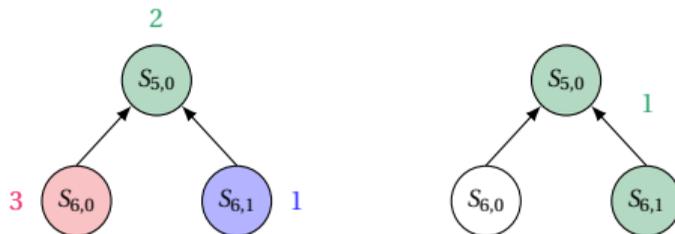
# Considering strategies

## Strategy $\mathcal{S}_X$ for a subgraph $X$

Procedure that allows to **enumerate** all the possible values that the S-boxes of  $X$  can take **under the differential constraints** imposed by the distinguisher.

**Parameters** of a strategy  $\mathcal{S}_X$ :

- number of solutions  $\mathcal{N}$ ;
- online time complexity  $\mathcal{T}$ .



A strategy can be further refined with extra information: e.g. **memory**, **offline time**.

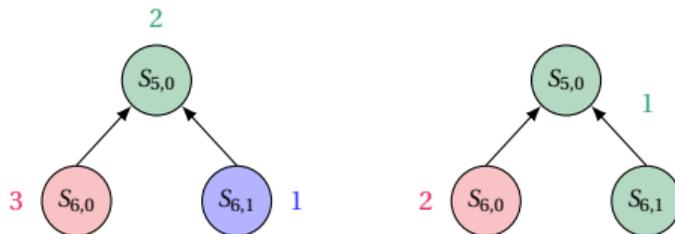
# Considering strategies

## Strategy $\mathcal{S}_X$ for a subgraph $X$

Procedure that allows to **enumerate** all the possible values that the S-boxes of  $X$  can take **under the differential constraints** imposed by the distinguisher.

**Parameters** of a strategy  $\mathcal{S}_X$ :

- number of solutions  $\mathcal{N}$ ;
- online time complexity  $\mathcal{T}$ .



A strategy can be further refined with extra information: e.g. **memory**, **offline time**.

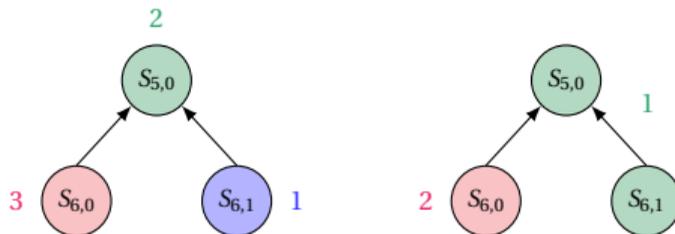
# Considering strategies

## Strategy $\mathcal{S}_X$ for a subgraph $X$

Procedure that allows to **enumerate** all the possible values that the S-boxes of  $X$  can take **under the differential constraints** imposed by the distinguisher.

**Parameters** of a strategy  $\mathcal{S}_X$ :

- number of solutions  $\mathcal{N}$ ;
- online time complexity  $\mathcal{T}$ .



A strategy can be further refined with extra information: e.g. **memory**, **offline time**.

**Objective:** Build an **efficient strategy** for the **whole graph**.

→ Based on **basic strategies**, i.e. strategies for a single S-box.

# Comparing two strategies

Compare two strategies  $\mathcal{S}_X^1$  and  $\mathcal{S}_X^2$  for the same subgraph  $X$

1. Choose the one with the **best time** complexity.
2. If same time complexity, choose the one with the **best memory** complexity.

Compare  $\mathcal{S}_X^1$  and  $\mathcal{S}_Y^2$  when  $Y \subset X$

If the **number of solutions** and **time complexity** of  $\mathcal{S}_X^1$  are **not higher** than those of  $\mathcal{S}_Y^2$ , then we can freely replace  $\mathcal{S}_Y^2$  by  $\mathcal{S}_X^1$ .

# Merging two strategies

Let  $\mathcal{S}_X$  and  $\mathcal{S}_Y$  two strategies for the graphs  $X$  and  $Y$  respectively.

- The **number of solutions** of  $\mathcal{S}' = \text{merge}(\mathcal{S}_X, \mathcal{S}_Y)$  **only depends** on  $X \cup Y$ :

Number of solutions of  $\mathcal{S}'$

$Sol(X \cup Y) = Sol(X) + Sol(Y) - \# \text{ bit-relations between the nodes of } X \text{ and } Y$  ⚠ log scale

Time and memory associated to  $\mathcal{S}'$

- $T(\mathcal{S}') \approx \max(T(\mathcal{S}_X), T(\mathcal{S}_Y), Sol(X \cup Y))$
- $M(\mathcal{S}') \approx \max(M(\mathcal{S}_X), M(\mathcal{S}_Y), \min(Sol(\mathcal{S}_X), Sol(\mathcal{S}_Y)))$

# A dynamic programming approach

---

- The **online time** complexity of  $merge(\mathcal{S}_X, \mathcal{S}_Y)$  **only depends** on the time complexities of  $\mathcal{S}_X$  and  $\mathcal{S}_Y$ .
- An **optimal strategy** for  $X \cup Y$  **can always** be obtained by **merging two optimal strategies** for  $X$  and  $Y$ .
- Use a **bottom-up approach**, merging first the strategies with the smallest time complexity to reach a graph strategy with a minimal time complexity.

## Dynamic programming approach

Ensure that, for any subgraph  $X$ , we only keep one optimal strategy to enumerate it.

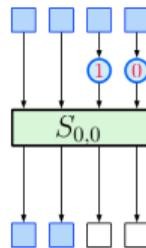
# Sieving

**Idea:** Use the differential constraints to filter out pairs that **cannot follow the differential**, regardless of the value of the key.

- Example:

$$(x_3, x'_3, x_2, x'_2, x_1 \oplus x'_1, x_0 \oplus x'_0)$$

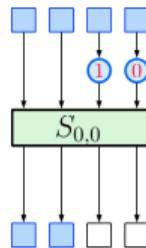
$$\text{Filter: } 36/2^6 = 2^{-0.83}.$$



# Sieving

**Idea:** Use the differential constraints to filter out pairs that **cannot follow the differential**, regardless of the value of the key.

- Example:  $(x_3, x'_3, x_2, x'_2, x_1 \oplus x'_1, x_0 \oplus x'_0)$   
Filter:  $36/2^6 = 2^{-0.83}$ .



## Pre-sieving

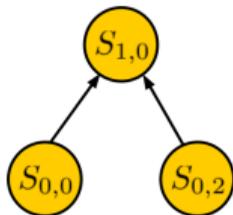
Apply a sieve on all **S-boxes of the external rounds**.

**Advantage :** The key recovery is performed on  $N' \leq N$  pairs.

# Precomputing partial solutions

## Idea

Precompute the partial solutions to some **subgraph**.

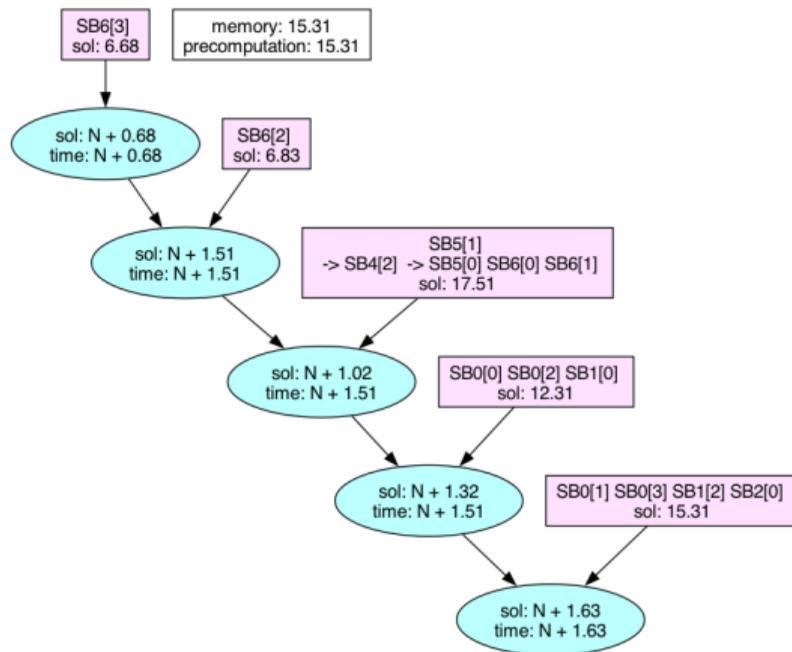


- **Impact** on the **memory complexity** and the **offline time** of the attack.
- The **optimal key recovery strategy** depends on how much memory and offline time are allowed.

# Applications of our tool: KYRYDI



# Application to the toy cipher



# Application to other ciphers

---

Start from an **existing distinguisher** that led to the best key recovery attack against the target cipher.

- **RECTANGLE**: Extended by **one round** the previous **best attack**.
- **PRESENT-80**: Extended by **two rounds** the previous **best differential attack**.
- **GIFT-64** and **SPEEDY-7-192**: Best key recovery strategy without additional techniques.

# Extensions and improvements

---

- Handle ciphers with **more complex linear layers**.
- Handle ciphers with **non-linear key schedules**.
- Incorporate **tree-based** key recovery techniques by exploiting the structure of the involved **S-boxes**.

The **best distinguisher** does not always lead to the **best key recovery!**

## Ultimate goal

Combine the tool with a **distinguisher-search** algorithm to find the best possible attacks.

# Other open problems

---

- Prove **optimality**.
- The tool works for (impossible) differential attacks:
  - Apply a similar approach to **other attacks**.

# Other open problems

---

- Prove **optimality**.
- The tool works for (impossible) differential attacks:
  - Apply a similar approach to **other attacks**.

Thanks for your attention!

Link to **KYRYDI**:

`https://gitlab.inria.fr/capsule/kyrydi`